Sensor2Scene: Foundation Model-driven Interactive Realities

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Outline

- Background & motivation
- Problem to solve: can we xxxx?
- Existing solution and challenges
- Our solution design
 - Part1: connecting the sensor data with scene descriptions
 - Part2: create the visualization of the scene with text-to-3D
- Results: demonstrations, compare different text-to-3D models
- Discussions
 - Findings: our approach shows the potential
 - Limitations: current text-to-3D is not good at the abstract content represent, cannot handle dynamic content, etc
- After this paper and future work

https://www.notion.so/yqg/Presentation-b319950476f74c5184497b193fa5286a ?pvs=4

Background: Sensor and Sensor Information

 \bigcirc Rich information on measuring the world

S Difficult for the average user to understand



Expanding World of Augmented Reality (AR)



AR for Enhancing Human Perception and Interaction in the Reality 4

Sensor2Scene: Scene Generation from Sensor Data with FMs



Part 1: Scene Description Generator

Goal: sensor \rightarrow scene description

Insights: LLM can be a powerful tool

- Zero or few shot classifier on sensory information
- Good for imagination and creations.



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- Temperature: High Heat: A temperature of Input 39°C is quite high... Discomfort... Input data \rightarrow Interpretation Wind: ... is considered a light breeze on the Beaufort wind scale. **Desired**: number \rightarrow perception Prompt Expert in visualization....{prev. response } Example: $39C \rightarrow hot$... A large wall canvas that responds Interpretation \rightarrow Scene Depicting **Output** 2. to changes in temperature by altering its colors ... A delicate wind chime is **Desired**: perception \rightarrow <u>Tangible objects</u> installed, which likely produces Example: hot \rightarrow large wall with colors melodious sounds with the breeze....

Part 2: Text Description to 3D Scene

Problem: Convert Scene Descriptions to 3D Objects

Approaches

- Approach 1: Custom Programming ?
 - High complexity; needs more programming skills.
- Approach 2: Text to 3D Conversion
 - **Challenge:** Models support only individual objects.
 - Steps:
 - i. Identify tangible objects and features (color, texture, size).
 - ii. Create individual 3D objects.
 - iii. Arrange objects in the environment.

... A **large wall** canvas that responds to changes in **temperature** by altering its **colors** ... A delicate **wind chime** is installed, which likely produces melodious sounds with the **breeze**. ...

Scene Description from Part 1



A large red wall

A delicate wind chime

Part 3: LLM Evaluator in the loop

Observations:

- 1. Response can be too descriptive.
- 2. Ignoring part of input data

Evaluator: Scoring the scene description based on

• Specificity, Utilization, Fidelity, Integration, Coherence

Input: Location: gym Humidity: 55.6%; Temperature: 27.65

The gym environment could be visualized with varying shades of red and orange to indicate the warmth of the space... They would notice the colors shifting subtly to reflect the temperature changes within the gym...

Vector DB: Recording good descriptions for future reference



System Implementation

Foundation Models

- Language Model: GPT-4
- Text-to-3D Model: Luma.AI[1], DreamGaussian[2]

AR Interface

- Backend: Flask-AFrame Server
- Rendering: WebXR

Device Support

• Supported Devices: Meta Quest 3, Vision Pro



Device Setup: AR Glasses and Smart-home Sensor

[1] LumaAI: http://lumalab.ai

[2] Tang, Jiaxiang, et al. "Dreamgaussian: Generative gaussian splatting for efficient 3d content creation." arXiv preprint arXiv:2309.16653 (2023).

Synthesized Scene



(a) Kansas – Fall

Temperature: 22C Humidity: 50% Air Quality: 30AQI



(b) Dubai – Summar

Temperature: 40C Humidity: 50%



(c) Iceland - Winter

Temperature:8C Light: 50Lux Humidity: 40%

Result on Real World Scene



Example 1: humidity 86%, noise: 75 dB



Example 2: humidity 32%, noise 75 dB

Key Takeaways & Limitations

Takeaways

- **LLM/LMM:** Bridges sensor data with scene creation.
- LLM Evaluation in the Loop: Five metrics for assessing scene descriptions.
- **Pipeline:** Data capture to AR visualization.

Limitations

- **Text-to-3D:** Challenges with abstract sensor information like smoke.
- Sensor Data Interpretation: Risk of misinterpretation by LLMs.

Next Step 1: 3DGS for Smoke/Hot Weather

Objective: Can we draw the volume of hot air or smoke?

Solution:

- 3D Gaussian Splatting (3DGS)
- Learn the abstraction content features, e.g., volume, colors, dynamics, etc.)



Next Step 2: Training Sensor Data Embedding with Visual Modality



3DGS ⇔ Visualization Space ⇐ Sensor Data

Thank You / Questions?

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